

SUTRON ACCUBAR® BAROMETRIC PRESSURE MULTIPLE INTERFACE SENSOR

OPERATIONS & MAINTENANCE MANUAL



MODEL 5600-0120-1,-2

PART NO. 8800-1036

REVISION F



SUTRON CORPORATION

22400 Davis Drive
GS-25F604D SBSA

Sterling, VA 20164
ISO 9001:2008 Certified

(703) 406-2800
(703) 406-2801 Fax

www.sutron.com & www.sutronwin.com/sutronwin/tw/
Sutron is an authorized Iridium Value Added Reseller (VAR).

page 1
3/22/2011

Table of Contents

1.	Introduction.....	3
2.	Quick Start	4
3.	Cabling	5
	Sutron-Supplied Cable.....	5
	Terminal Strip	5
	SDI-12 Wiring.....	6
	RS-232 Wiring	6
	Analog Wiring.....	7
4.	Setup and Operation	8
	Introduction	8
	Nomenclature	8
	Setting the Address.....	8
	Using Switches to Set the Address.....	9
	Using a command to Set the Address.....	9
	Verifying the Address and Operation	10
	Commands (Overview).....	11
	Making a Measurement	12
	Selecting a measurement command class	12
	Always supported.....	12
	Multiple long measurement time sensors	12
	Improved data integrity checking.....	12
	Making a non-concurrent Measurement (M command)	12
	Making a Concurrent Measurement (C command)	14
	Making a non-concurrent Measurement with CRC-16 (MC command).....	15
	Making a Concurrent Measurement with CRC-16 (CC command).....	16
	Other Measurements	18
	Changing the Units.....	18
	Setting User Units	19
	Setting Station Elevation.....	19
	Analog Output Range.....	20
	Converting Voltage to Pressure.....	21
	Configuring the Operating Mode and Averaging Time	22
	Setting the Operating Mode	22
	Setting the Averaging Time.....	22
	Resetting the unit to Factory Default Configuration.....	23
5.	Command Reference.....	24
	Accubar Basic SDI-12 Commands.....	24
	Accubar Extended Commands	33
	Additional commands for Analog output units (-2).....	36
6.	Installation	37
7.	Calibration	38
	Factory Calibration.....	38
	Metrology Lab Calibration	38
8.	Troubleshooting and Maintenance.....	40

Troubleshooting	40
Additional Troubleshooting commands	40
Measure Break detect time.....	40
Test Analog output.....	41
Maintenance	41
9. Specifications for 5600-0120 Barometric ACCUBAR®	42
Appendix A -- Introduction to Pressure Measurement	44
Appendix B-- Sutron Customer Service Policy	48
Appendix C-- Commercial Warranty.....	49
SUTRON MANUFACTURED EQUIPMENT	49
NON-SUTRON MANUFACTURED EQUIPMENT	49
REPAIR AND RETURN POLICY	49
EXTENDED WARRANTY AND ON-SITE MAINTENANCE.....	49

1. Introduction

The 5600-0120 ACCUBAR[®] Pressure Sensor is a solid-state pressure transducer suitable for data collection and monitoring applications. The ACCUBAR[®] sensor has been designed with the following features to operate in a wide range of applications:

low power consumption (-1)	standby power is 0.2mA, average power when taking measurements every 15 minutes via SDI-12 is less than 0.25 mA.
high accuracy	0.5 mB (hPa)
full temperature compensation	the accuracy is maintained over the temperature range of -40° to +60°C.
selectable units	the sensor can be configured to output the data in mB, hPa, kPa, "Hg, mmHg, Atm, and psi.
non-volatile setup	the setup is stored in EEROM and remains even when power is removed from the sensor
wide operating voltage	the sensor operates over the voltage range of 8 to 28 VDC

2. Quick Start

The ACCUBAR[®] sensor comes with a cable and setup compatible with a Sutron 8200. If you have an 8200, you are able to operate the ACCUBAR[®] without making any changes to the wiring or setup. If you do not have an 8200, you will need to change the wiring to make it connect to your system as described in Chapter 3.

To use the ACCUBAR[®] with the 8200 follow these simple steps:

- Connect the sensor to your Sutron 8200 Data Logger SDI-12 port on the front panel of the 8200, using the factory supplied cable.
- Use the 8200 SYSTEM SETUP\ENABLE SENSOR menu to turn SDI0-1 ON. If you want to see the units indicator for the measurement also turn SDI0-2 ON. Refer to the [Sutron 8200 Data Logger Operations and Maintenance Manual](#) if you do not know how to ENABLE sensors.
- Use the 8200 VIEW\LIVE READINGS menu and select the SDI0-1 sensor.

The 8200 will now display the pressure readings from the ACCUBAR[®] sensor in units of milliBars (mB) and hectoPascals (hPa). **Note: These two units of measure are equivalent.**

3. Cabling

Sutron-Supplied Cable

The ACCUBAR[®] comes with a cable pre-wired to an internal terminal strip which has a DB9M connector on it. This cable will plug into a Sutron 8200. The wiring of the cable is as follows. Note the two different possibilities for the colors of the conductors.

Name	Terminal	Color Opt 1	Color Opt 2	DB9M Pin
Ground	1	Blue	Yellow	5
RxD	2	Yellow	Red	3
TxD	3	Orange	Brown	2
Battery	4	Black	Gray	9
Ground	5	Gray	Blue	7
SDI Data	6	Red	Black	1
DTR	7	Green	Orange	4
Analog Out +	8	Purple	Green	6
Analog Out –	9	White	Violet	8

Analog output is only available on -2 versions of the ACCUBAR[®].

Terminal Strip

The ACCUBAR[®] has a terminal strip to which you can connect a cable to interface to the sensor. To access the terminal strip, use a screwdriver and remove the cover of the sensor. The terminal strip is located on the PCB. The terminal strip has 9 connections which are as follows:

Name	Terminal	Unit Type
Ground	1	-1 and -2
RxD	2	-1 and -2
TxD	3	-1 and -2
Battery (8 to 28 volts)	4	-1 and -2
Ground	5	-1 and -2
SDI Data	6	-1 and -2
DTR	7	-1 and -2
Analog Out +	8	-2 only
Analog Out –	9	-2 only

Terminal connection 1 is labeled with a 1 on the printed circuit board next to the terminal strip. The analog output is only available on the -2 unit.

SDI-12 Wiring

The SDI interface conforms to SDI-12 standard version 1.0 through 1.3. Only three wires are needed to use the ACCUBAR[®] SDI-12 interface. The following table contains pin descriptions for the J5 terminal block inside the ACCUBAR[®]:

Description	J5 Terminal	Data Recorder Connection
Battery	4	Connect to Battery or data recorder supplied voltage
Ground	5	Connect to Ground
SDI Data	6	Connect to data recorder SDI Data line

RS-232 Wiring

The default communications parameters for RS-232 are:

- 1200 baud
- 7 data bits with even parity added as an eighth bit
- One stop bit

The following table contains pin descriptions for the J5 terminal block inside the ACCUBAR[®], with the corresponding RS-232 cable connections to PC.

Description	J5 Terminal	IBM AT Connection (DB-9F cable)	IBM PC or any DTE Connection (DB-25-F cable)
Ground	1	5	7
Receive Data	2	3	2
Transmit Data	3	2	3
Battery	4	Supply Voltage	Supply Voltage
Ground	5	Supply Ground	Supply Ground
SDI Data	6		
DTR	7	4	20

When Data Terminal Ready (DTR) is off, the ACCUBAR[®] enters a low-power standby mode and the RS-232 drivers are turned off. When DTR is raised, the unit resumes normal operation.

NOTE: The unit can be powered off of the DTR pin but a typical RS-232 connector will not supply enough current to power the unit and an external supply will be required. Supply Voltage and Supply Ground are where the supply voltage for the ACCUBAR[®] is applied, if necessary.

Even though the unit can be powered off of the DTR pin, the DTR and Battery pins (4 and 7) are NOT interchangeable. The DTR line must be high for the ACCUBAR[®] to acknowledge an RS-232 connection. Pins 1 and 5 are connected internally and are interchangeable. The two connections are provided as a convenience to the RS-232 user.

Analog Wiring

The analog output is a 0 to 5V output with settable range. The following table contains pin descriptions for the J5 terminal block inside the ACCUBAR®.

Description	J5 terminal	Connection
Battery	4	Connect to Battery + or data recorder supplied voltage
Ground	5	Connect to Battery - or data recorder ground
Analog out +	8	Connect to Analog + input
Analog out -	9	Connect to Analog - input

NOTE: Analog out - is connected internally to ground. The analog out - pin is provided to allow the unit to be connected to a differential input and eliminate errors due to the voltage drop in the ground connection on long cable runs.

4. Setup and Operation

Introduction

This section will familiarize you with the steps and commands needed to alter the setup of the ACCUBAR[®]. If you will use the ACCUBAR[®] sensor at address 0 (the factory default) and can accept the output in units of mB (hPa), you will not need to use these commands. Typically, you will need to issue some of the commands, so we recommend you learn how to do so. Learning to issue commands also helps if you need to troubleshoot a sensor.

Users of the analog version (5600-0120-2) of the ACCUBAR[®] will not need to use these commands if the output range of 600 to 1100 mB is acceptable. Users of the analog version will, however, probably wish to customize the output range to suit their application. To customize the output range, analog users will need to know how to issue commands.

To issue commands to the ACCUBAR[®] via SDI-12, you will need to connect it to a data recorder, such as a Sutron 8210, 8310, 9210, or Xpert which is capable of issuing standard and extended SDI-12 commands. Follow the instructions in Sections 2 and 3 in order to make these connections.

To issue commands to the ACCUBAR[®] via RS-232, you will need to connect it to an RS-232 terminal or to a computer running terminal emulation (communications) software. Follow the instructions in Section 3 in order to make these connections

Nomenclature

All commands have three components: the **device address**, the **command body**, and the **command termination**.

The **device address** is a single character and is the first character of a command. In the examples that follow, it is usually the number 0 (the default address as shipped from the factory).

The **command body** and the responses are shown as a combination of upper and lower case letters. The upper case letters are the fixed portions of the command and the lower case letters are the variables or values. In the specific examples, you will see that the lower case letters are replaced with actual numbers.

All commands are shown with an exclamation point (!) as the **command terminator**. This command terminator works with both the SDI-12 and RS-232 interfaces. With RS-232, you have the additional option of terminating the command with a carriage return <CR> and/or line feed <LF> in place of the exclamation point.

Setting the Address

If you are using the ACCUBAR[®] connected with other SDI-12 devices, you will need to change the ACCUBAR[®] address. Otherwise, skip this section. The address simply lets multiple devices share the same wiring. When the data recorder needs data from a particular sensor, it requests data using an address. Only the device with the matching address will reply. For convenience in setting up the unit when only one sensor is connected, the ACCUBAR[®] supports wildcard addresses of asterisk (*) and question mark (?).

The default address is 0. There are two ways to set the address: switches and command.

Using Switches to Set the Address

NOTE: It is usually easier to set the address via a software command, as described in the next section.

Remove the cover for the sensor and set the switches to one of the settings as follows:

Address	Switch 4	Switch 3	Switch 2	Switch 1
0	<i>off</i>	<i>Off</i>	<i>off</i>	<i>off</i>
1	<i>off</i>	<i>Off</i>	<i>off</i>	ON
2	<i>off</i>	<i>Off</i>	ON	<i>off</i>
3	<i>off</i>	<i>Off</i>	ON	ON
4	<i>off</i>	ON	<i>off</i>	<i>off</i>
5	<i>off</i>	ON	<i>off</i>	ON
6	<i>off</i>	ON	ON	<i>off</i>
7	<i>off</i>	ON	ON	ON
8	ON	<i>Off</i>	<i>off</i>	<i>off</i>
9	ON	<i>Off</i>	<i>off</i>	ON
A	ON	<i>Off</i>	ON	<i>off</i>
B	ON	<i>Off</i>	ON	ON
C	ON	ON	<i>off</i>	<i>off</i>
D	ON	ON	<i>off</i>	ON
E	ON	ON	ON	<i>off</i>
F	ON	ON	ON	ON

Note: all other switches in the ACCUBAR[®] need to be OFF. The factory default for all switches is OFF (address 0). The ACCUBAR[®] will not operate properly if any of the switches (5 to 8) are set ON.

Using a command to Set the Address

In order to set the address by SDI-12 command or RS-232 command, the DIP switch address must be set to 0 (Switches 1,2,3,4 OFF). This is the factory setting for the switches. Also, no other SDI-12 devices connected to the system should be set to address 0 or to the desired ACCUBAR[®] address. Hint: if you do not know the address of a particular ACCUBAR[®], use the unknown address command to have the ACCUBAR[®] identify itself.

NOTE: There can only be one ACCUBAR[®] connected in order for the unknown address command to work. The syntax for the unknown address command is

*X?!

The ACCUBAR[®] also supports an alternate version of the unknown address command which is a command acknowledge to a wildcard address. The syntax for this version is:

*!

Beginning with version 1.2 of the SDI-12 specification there is an address query command defined. Therefore another version of the request unknown address or address query command is:

?!

The SDI-12 command for setting the ACCUBAR[®]'s address is the XAD command

Bringing the Benefits of Real-Time Data Collection to the World

Sutron Corporation, 22400 Davis Drive, Sterling, Virginia 20164-4444

<u>0XADnAn!</u>	where a is the current address of the device, n is the new SDI-12 address and n is the same address repeated (0 to 9, ;;<=>?,A to Z,a to z).
-----------------	--

Note that the command follows the SDI-12 standard beginning with the address and ending with "!".

The ACCUBAR[®] will issue a reply message in response to the command if the command was recognized. The message will be 00011 which is explained in the Command Reference. If you do not get this message, try the command again and check the switches (Unit must be set to address 0 since that is the address this command trying to change from). Note: The ACCUBAR[®] will not respond if the command is invalid, i.e., there is a typing mistake in the command or the two copies of the new address do not match.

As an example, the following command would set the ACCUBAR[®] address to 5:

0XAD5A5!

Subsequently, the address can be set to a different address, 9 for example, by the command:

5XAD9A9!

The ACCUBAR[®] also supports an alternate version of the set Address command as specified in SDI-12 standard version 1.2.

<u>0An!</u>	where 0 is the current address of the device, n is the new SDI-12 address (0 to 9, A to Z, a to z).
-------------	---

As an example, the following command would set the ACCUBAR[®] address to 5:

0A5!

The ACCUBAR[®] will respond with the new address which is 5.

Subsequently, the address can be set to a different address, 9 for example, by the command:

5A9!

Verifying the Address and Operation

The ACCUBAR[®] will respond with an identifying message when it receives the *send identification* command, I. The format of the command is:

<u>aI!</u>	Where a is the address for the ACCUBAR [®] .
------------	---

The ACCUBAR[®] will reply with

<u>a13 SUTRON 0120-11.0ssssssVvvv</u>	Where:
a	SDI-12 address
13	supports SDI version 1.3 commands
SUTRON	manufacturer SUTRON
0120-1	Sutron model number
1.0	hardware revision level
ssssss	sensor serial number
Vvvv	the software revision

If you do not get a reply, check the address setting for the ACCUBAR[®] and make sure you use the proper address for the sensor.

Commands (Overview)

The commands to set up and operate the ACCUBAR[®] are those defined by the SDI specifications 1.0 plus some extended commands defined by Sutron. All commands start with a single-character address and end in an exclamation point. The address is a single character with values 0 to 9, ;,<=> ?, A to Z, and a to z. Values are entered in the form of a polarity (+ or -) sign followed by up to seven digits, including a decimal point. The commands are in ASCII and all the replies use printable ASCII characters followed by <CR> <LF>.

The ACCUBAR[®] replies to all SDI commands it supports. If the ACCUBAR[®] receives a command it does not support, no reply is made. The reply will have one of two forms:

a0000 where a is the address and the 0000 indicates that there is no further message to send

or

atttn where a is the address, ttt is the amount of time, in seconds, the ACCUBAR[®] needs to make the measurement or process the command and n is the number of values that can be collected. In this form the sensor will also respond with its address when the data is ready to collect. This response is called a service request.

and

a

If you issued the *change address* command or the *identify* command described in the previous sections, you already have some experience with using ACCUBAR[®] commands. There are other commands available to make measurements, set the type of output units for the measurements, perform special scaling of the measurements, etc. The following sections describe the commands by function.

Making a Measurement

There are four classes of measurement commands which will be referred to as M commands (Measurement Commands), C commands (Concurrent Measurement Commands), MC commands (Measurement commands with CRC-16), and CC commands (Concurrent Measurement Commands with CRC-16). Concurrent measurement commands are new to version 1.2 of the SDI-12 specification. The commands with CRC-16 are new to version 1.3 of the SDI-12 specification. In the original class of “M” measurement commands, the data recorder issued the measurement command and then waited for the sensor to complete the measurement before continuing the data collection cycle. Only one sensor could be accessed at a time and a maximum of nine parameters could be returned. With version 1.2 of the specification, concurrent measurements were defined. With a concurrent measurement, the data recorder can request the sensor to take a measurement, determine how long it will be until the sensor has a reading, and then continue on making requests to other sensors on the SDI-12 bus. This way multiple sensors are taking measurements concurrent with each other. Once the measurement time for a sensor has expired the data recorder polls the sensor for the data. The CRC-16 commands that were added in version 1.3 of the specification add a 16 bit cyclic redundancy check (CRC-16) to the returned data values. This provides an additional means for the data recorder to ensure that the collected data has not been corrupted. Software support for SDI-12 version 1.3 was added in software revision V2.0. Version V1.9 and before only support the M commands.

Selecting a measurement command class

Always supported

The first requirement is that the data recorder support the command. All SDI-12 data recorders support the non-concurrent measurement M command. With the M command the data recorder collects data from the sensors one at a time.

Multiple long measurement time sensors

When collecting data from several SDI-12 sensors that have long measurement times, the complete data collection cycle can be shortened by utilizing concurrent commands. The data recorder can initiate the measurement on all the sensors and when each finishes, then collect the data from all of them. Since the measurement times overlap, the complete data collection cycle is shorter. There is no advantage to the concurrent measurement C command when there is only one sensor.

Improved data integrity checking

The measurement command classes with CRC-16 (MC and CC) offer additional data integrity checking over the non CRC-16 commands (M and C). The non CRC-16 commands offer data integrity checking in the form of parity and the SDI-12 command structure. The CRC-16 commands offer some additional data integrity through the addition of a CRC-16. Since the CRC-16 commands are brand new in SDI-12 version 1.3, not as many data recorders support them. In most applications, lack of this support on the part of the data recorder will not be missed since non CRC-16 SDI-12 commands still offer significant data integrity checking. If the data recorder supports CRC-16 commands, then it is recommended to use them when collecting data from this sensor in order to benefit from the increased noise immunity.

Making a non-concurrent Measurement (M command)

The command to tell the ACCUBAR[®] to make a measurement with the original measurement command is:

<u>aM!</u>	where a is the address character, and M is the command to make a measurement
------------	--

Most data recorders will issue this command and automatically handle the reply to collect data. You can also issue the command yourself. In reply, the ACCUBAR[®] will respond with

<u>attt2</u>	acknowledging it is address a and indicating that after ttt seconds are allowed for the measurement, 2 values can be collected.
--------------	---

When the measurement is complete, the ACCUBAR[®] responds with a service request

<u>A</u>	where a is the address character
----------	----------------------------------

Note that you still don't have any data from the ACCUBAR[®]. To request the data after a measurement,

<u>aD0!</u>	where a is the address character and D0 is the command to retrieve measured data. (Note: 0 is zero, not the letter O)
-------------	---

In this case the ACCUBAR[®] will reply with two values in the format:

<u>avu</u>	where a is the address, v is the data value and u indicates the units. Both v and u have the format of a polarity (+ or -) sign followed by up to seven digits, including a decimal point. One example of a response would be 0+1013.25+0
------------	--

The u indicates the units of the measurement. When u is 0, the value has units of mB(hPa). When u is 1, the units are inches of mercury ("Hg). When u is 9, the units depend on a user entered slope and offset. u can also take on additional values if a station elevation offset has been entered. The following table summarizes all the values of u.

- 0 units are mB (hPa)
- 1 units are "Hg
- 2 units are kPa
- 3 units are mmHg
- 4 units are Atm
- 5 units are psia
- 9 units depend on user-entered scale and offset.

If the station elevation offset is non-zero, then one of the following values of u will be returned:

- 10 units are mB + station elevation offset
- 11 units are "Hg + station elevation offset
- 12 units are kPa + station elevation offset
- 13 units are mmHg + station elevation offset
- 14 units are Atm + station elevation offset
- 15 units are psia + station elevation offset
- 19 user units with non-zero station elevation offset
(mB + elevation offset) * user scale + user offset
set by XE or XS Set by XU

In most cases, you will not set up the recorder to store this units identifier. It is provided in response to the standard measure command to eliminate confusion as to the computation used to come up with the final value.

Making a Concurrent Measurement (C command)

The command to tell an ACCUBAR[®] to make a concurrent measurement is:

<u>aC!</u>	where <u>a</u> is the address character, and <u>C</u> is the command to make a concurrent measurement
------------	---

The concurrent measurement command was first defined in version 1.2 of the SDI-12 specification. Therefore the data recorder will have to be SDI-12 version 1.2 or higher compliant before it can be expected to issue this command and automatically handle the reply to collect data. You can also issue the command yourself. In reply, the sensor will respond with

<u>attt02</u>	Acknowledging it is address <u>a</u> and indicating that after <u>ttt</u> seconds are allowed for the measurement, <u>2</u> values can be collected.
---------------	--

When the measurement is complete, the sensor does NOT issue a service request Note: this is different from the M command.

To request the data after a measurement,

<u>aD0!</u>	where <u>a</u> is the address character and <u>D0</u> is the command to retrieve measured data. Note: the number zero follows D, not the letter O.
-------------	--

In this case, the ACCUBAR[®] will reply with two values in the format:

<u>avu</u>	where <u>a</u> is the address, <u>v</u> is the data value and <u>u</u> indicates the units. Both v and u have the format of a polarity sign (+ or -) followed by up to seven digits, including a decimal point.
------------	---

The u indicates the units of the measurement. When u is 0, the value has units of mB(hPa). When u is 1, the units are inches of mercury ("Hg). When u is 9, the units depend on a user entered slope and offset. u can also take on additional values if a station elevation offset has been entered The following table summarizes all the values of u.

- 0 units are mB (hPa)
- 1 units are "Hg
- 2 units are kPa
- 3 units are mmHg
- 4 units are Atm
- 5 units are psia
- 9 units depend on user-entered scale and offset.

If the station elevation offset is non-zero, then one of the following values of u will be returned:

- 10 units are mB + station elevation offset
- 11 units are "Hg + station elevation offset
- 12 units are kPa + station elevation offset
- 13 units are mmHg + station elevation offset
- 14 units are Atm + station elevation offset
- 15 units are psia + station elevation offset
- 19 user units with non-zero station elevation offset
(mB + elevation offset) * user scale + user offset
set by XE or XS Set by XU

In most cases, you will not set up the recorder to store this units identifier. It is provided in response to the standard measure command to eliminate confusion as to the computation used to come up with the final value.

Making a non-concurrent Measurement with CRC-16 (MC command)

The command to tell the ACCUBAR[®] to make a non-concurrent measurement with a CRC-16 check on the data is:

<u>aMC!</u>	where <u>a</u> is the address character, and <u>MC</u> is the command to make a non-concurrent measurement with a CRC-16
-------------	--

The non-concurrent measurement with CRC-16 command was first defined in version 1.3 of the SDI-12 specification. Therefore the data recorder will have to be SDI-12 version 1.3 or higher compliant before it can be expected to issue this command and automatically handle the reply to collect data. You can also issue the command yourself. In reply, the ACCUBAR[®] will respond with

<u>att2</u>	acknowledging it is address <u>a</u> and indicating that after <u>ttt</u> seconds are allowed for the measurement, <u>2</u> values can be collected.
-------------	--

When the measurement is complete, the sensor responds with a service request

<u>a</u>	where <u>a</u> is the address character
----------	---

Note that you still do not have any data from the ACCUBAR[®]. To request the data after a measurement,

<u>aD0!</u>	where <u>a</u> is the address character and <u>D0</u> is the command to retrieve measured data. Note: the number zero follows D, not the letter O.
-------------	--

In this case, the sensor will reply with two values in the format:

<u>av</u> <u>C</u>	where <u>a</u> is the address, <u>v</u> is the data value, <u>u</u> indicates the units, and <u>C</u> is the CRC-16 encoded into 3 ASCII characters. Both v and u have the format of a polarity sign (+ or -) followed by up to seven digits, including a decimal point. The CRC-16 is always the last three characters which are never a numeric digit.
--------------------	--

The u indicates the units of the measurement. When u is 0, the value has units of mB(hPa). When u is 1, the units are inches of mercury ("Hg). When u is 9, the units depend on a user entered slope and offset. u can also take on additional values if a station elevation offset has been entered. The following table summarizes all the values of u.

- 0 units are mB (hPa)
- 1 units are "Hg
- 2 units are kPa
- 3 units are mmHg
- 4 units are Atm
- 5 units are psia
- 9 units depend on user-entered scale and offset.

If the station elevation offset is non-zero, then one of the following values of u will be returned:

- 10 units are mB + station elevation offset
- 11 units are "Hg + station elevation offset
- 12 units are kPa + station elevation offset
- 13 units are mmHg + station elevation offset
- 14 units are Atm + station elevation offset
- 15 units are psia + station elevation offset
- 19 user units with non-zero station elevation offset
(mB + elevation offset) * user scale + user offset
set by XE or XS Set by XU

In most cases, you will not set up the recorder to store this units identifier. It is provided in response to the standard measure command to eliminate confusion as to the computation used to come up with the final value.

Making a Concurrent Measurement with CRC-16 (CC command)

The command to tell the ACCUBAR[®] to make a concurrent measurement with CRC-16 check on the data is:

<u>aCC!</u>	where <u>a</u> is the address character, and <u>CC</u> is the command to make a concurrent measurement with a CRC-16 check on the returned data
-------------	---

The concurrent measurement with CRC-16 command was first defined in version 1.3 of the SDI-12 specification. Therefore the data recorder will have to be SDI-12 version 1.3 or higher compliant before it can be expected to issue this command and automatically handle the reply to collect data. You can also issue the command yourself. In reply, the ACCUBAR[®] will respond with

<u>attt02</u>	acknowledging it is address <u>a</u> and indicating that after <u>ttt</u> seconds are allowed for the measurement, <u>2</u> values can be collected.
---------------	--

When the measurement is complete, the sensor does NOT issue a service request Note: this is different from the M and MC commands.

To request the data after a measurement,

<u>aD0!</u>	where <u>a</u> is the address character and <u>D0</u> is the command to retrieve measured data. Note: the number zero follows D, not the letter O.
-------------	--

In this case, the sensor will reply with two values in the format:

<u>avuC</u>	where <u>a</u> is the address, <u>v</u> is the data value, <u>u</u> indicates the units the value is expressed in, and <u>C</u> is the CRC-16 encoded into 3 ASCII characters. Both v and u have the format of a polarity sign (+ or -) followed by up to seven digits, including a decimal point. The CRC-16 is always the last three characters which are never a numeric digit.
-------------	--

The u indicates the units of the measurement. When u is 0, the value has units of mB(hPa). When u is 1, the units are inches of mercury ("Hg). When u is 9, the units depend on a user entered slope and offset. u can also take on additional values if a station elevation offset has been entered The following table summarizes all the values of u.

- 0 units are mB (hPa)
- 1 units are "Hg
- 2 units are kPa
- 3 units are mmHg
- 4 units are Atm
- 5 units are psia
- 9 units depend on user-entered scale and offset.

If the station elevation offset is non-zero, then one of the following values of u will be returned:

- 10 units are mB + station elevation offset
- 11 units are "Hg + station elevation offset
- 12 units are kPa + station elevation offset
- 13 units are mmHg + station elevation offset
- 14 units are Atm + station elevation offset
- 15 units are psia + station elevation offset
- 19 user units with non-zero station elevation offset
(mB + elevation offset) * user scale + user offset
set by XE or XS Set by XUU

In most cases, you will not set up the recorder to store this units identifier. It is provided in response to the standard measure command to eliminate confusion as to the computation used to come up with the final value.

Other Measurements

The SDI-12 standard allows for other measurement commands such as M1, M2 etc., other current measurement commands such as C1, C2, etc., other non-concurrent measurements with CRC-16 such as MC1, MC2, etc, and other concurrent measurement with CRC-16 such as CC1, CC2, etc. This unit maintains symmetry across all four classes of commands, that is, it returns the same information to a C1 as it does to a M1 or a MC1 or a CC1. The ACCUBAR[®] supports the following optional measurement commands:

<u>aM1!</u> <u>aC1!</u> <u>aMC1!</u> <u>aCC1!</u>	measure mB (hPa) using factory calibration. Do not apply any user scaling, station elevation or offsets. This returns 1 value and the units are fixed to mB (hPa).
<u>aM2!</u> <u>aC2!</u> <u>aMC2!</u> <u>aCC2!</u>	measure temperature (Celsius or Farenheit). This returns two values: the temperature and the units. The units will be 0 for Celsius and 1 for Farenheit.
<u>aM3!</u> <u>aC3!</u> <u>aMC3!</u> <u>aCC3!</u>	measure user scale, user offset, elevation offset. Use this if you want to view the user-entered values that can affect the value returned by the M command.
<u>aM4!</u> <u>aC4!</u> <u>aMC4!</u> <u>aCC4!</u>	measure calibration lab scale and offset. Use this if you want to view the calibration lab values that can affect the value returned by the M, C, MC, and CC commands.
(Version 2.0 and higher.) <u>aM6!</u> <u>aC6!</u> <u>aMC6!</u> <u>aCC6!</u>	Measure temperature and pressure. The output is the concatenation of the M2 and M commands. Temperature, temperature units, Pressure, Pressure units.
(Version 2.0 and higher.) <u>aM7!</u> <u>aC7!</u> <u>aMC7!</u> <u>aCC7!</u>	Measure mB and degrees C using factory calibration. Do not apply any user scaling, field calibration or offsets. This returns two values and the units are fixed to mB and degrees C.

Remember to issue the aD0! command after the measurement is complete in order to retrieve the data.

Changing the Units

As noted above, the aM! command can return the pressure in several different units. The selection of the units is made using the XUPcommand:

<u>aXUP+n+d!</u>	where n is one of the selections from the following table and d is the number of digits to the right of the decimal point.
------------------	--

N	Type Units	Comments
0	mB (hPa)	
1	inches of mercury	
2	kPa	
3	mmHg	
4	Atm	
5	psia	
9	user units	the value has units that depend on the values entered using the XU command.

For example, the command

aXUP+0+2!

will specify the output to be in the default units (mB) with a resolution of 2 decimal places. The second parameter (2 in the example) is optional. If omitted, the resolution is not changed.

Setting User Units

If you want the sensor to read out in units other than the factory-programmed units, you will need to use the XUP command to set the units to 9, user units. When user units are selected, the software will use the equation:

$$\text{output} = \text{mB} * \text{scale} + \text{offset}$$

where scale and offset are values you can enter into the system.

The XU command is used to enter the user scale and offset. The format of the command is:

<u>aXUUs!</u>	where s is the signed scale and o is the signed offset.
---------------	---

For example, the following command will set the scale to 70.32 and the offset to 0.0:

aXUU+70.32+0

Similarly, the slope and offset can be set to any values that will produce the desired units.

NOTE: Remember that both a XU and a XUP command are required for the ACCUBAR® to report in user-defined units.

Setting Station Elevation

The ACCUBAR® will usually be installed at an elevation other than sea level. To have the ACCUBAR® report the atmospheric pressure at sea level, the sensor's elevation offset from sea level must be entered. The ACCUBAR® has two commands that can be used to enter this elevation offset. The XE command allows direct setting of an elevation offset which will be added to the measurement to compute atmospheric pressure at sea level:

<u>aXEou!</u>	where o is adjustment value with units u. u can have units 0=mB (hPa), 1="Hg, 2=kPa, 3=mmHg, 4=Atm, 5=psia, or 9=user units.
---------------	--

For example, the command:

aXE+20.2+0!

would set the elevation offset pressure to 20.2 with units of mB (hPa).

The other command used to set the elevation offset is the XS command. This command causes the sensor to make pressure readings and automatically compute a new elevation offset. You can use this command only if you have a stable, known pressure on the sensor. The command has the format:

<u>aXSdu!</u>	use this form when the sensor is at a stable, known pressure. The d represents the desired reading and u the units.
---------------	---

If the sensor was stable at 1005.23 mB, the following command would adjust the elevation offset to insure the 1005.23 mB reading:

0XS+1005.23+0!

If the sensor was under pressure and stable at 29.921 inches of mercury, the following command would adjust the elevation to ensure the 29.921" Hg reading:

0XS+29.921+1!

When the ACCUBAR[®] is done with the self-calibration, the new elevation offset is stored into memory. A subsequent aD0! command will display this offset in units of mB. The offset can also be displayed using the M3 command. The returned value will be in the current units of pressure.

Analog Output Range

The -2 version supports analog output. The output range is 0 to 5 volts. As shipped from the factory, this corresponds to 600 to 1100 mB. The analog output is driven by a 12 bit D/A converter. This means that the output changes in discrete steps of about 1.25 mV. Analog transmission of data is less accurate than digital transmission. There are three contributors to this error: Error in the transmitted value; noise and voltage drops picked up during transmission through the cable; conversion errors at the receiving end. For the ACCUBAR[®], the error in the transmitted value is going to be the error in the digital value plus a voltage error of the output. For the receiving end (data recorder, logger, panel display), there is a quantization error plus an accuracy error when the analog voltage is converted to a digital value. The best resolution of a 12 bit A/D on a 0 to 5 scale is 1.25 mV. If the scale is wider or the number of bits is less, then the resolution is even coarser.

Most users will want to customize the output range to maximize the accuracy of their equipment over the range of interest. With 600 to 1100 mB corresponding to 0 to 5V, a 1 mV error corresponds to a 0.1 mB

error. If the range is narrowed to 980 to 1030 mB then 1 mV error corresponds to a 0.01 mB error. The narrower range would also mean that it would take 100 mV of noise to generate a 1 mB error instead of the 10 mV that would be required with the 600 to 1100 mB range. Therefore to maximize the accuracy of data collected or displayed via the analog output, adjust the output range of the ACCUBAR[®] to match the range of pressures of interest. The command to set the Analog Output range is the

aXARzf!	where a is the address character, XAR is the extended command to set the analog range, z is the pressure in mB (hPa) that is to correspond to 0.000 VDC, and f is the pressure in mB (hPa) that is to correspond to 5.000 VDC.
---------	--

If the user wanted the output of the ACCUBAR[®] to be 800 to 1100 mB then the following command would adjust the range.

0XAR+800+1100!

If the user wanted the ACCUBAR[®] to output V1 volts at pressure P1 and V2 volts at pressure P2, then the following formulas would be used to determine z and f.

$$z = P1 - \frac{V1(P2 - P1)}{V2 - V1}$$

$$f = P1 + \frac{(5 - V1)(P2 - P1)}{(V2 - V1)}$$

For example, suppose you want the ACCUBAR[®] to output 2V at 29" Hg and 4V at 31" Hg. First you would convert "Hg to mB by multiplying by 33.864. This gives V1=2V, V2=4V, P1= 982.056, P2= 1049.784. Therefore

$$z = 982.056 - (2*(1049.784-982.056) / (4-2)) = 914.328$$

$$f = 982.056 + ((5-2)(1049.784-982.056) / (4-2)) = 1083.648$$

The command would therefore be:

0XAR+914.328+1083.648!

Converting Voltage to Pressure

The formula for converting analog output voltage to pressure is:

$$\text{Pressure} = \text{analog output} * \text{Slope} + \text{offset}$$

where the slope is (5 volt pressure value - 0 volt pressure value) / 5
and the offset is the 0 volt pressure value.

For the above illustrated range of 2V at 29" Hg and 4V at 31"Hg the offset for reading the pressure in mB would be **z** which was 914.328. The slope would be **(f - z) / 5** which is: 33.864. To compute the output in "Hg for this example, the slope would be 1 and the offset would be 27.

The slope and offset for different units when the output is configured for 600 to 1100 mB is given in the following table:

UNITS	slope	Offset
mB (hPa)	100	600
"Hg	2.953	17.718
kPa	10	60
mmHg	75	450
PSIA	1.4504	8.7023

NOTE: The analog output voltage does take into account the elevation offset (set by the XE or XS commands). Therefore if the unit's elevation has been entered, it outputs the absolute pressure corrected to sea level as opposed to the site specific pressure. In other words, the analog output pressure is the same as the pressure the measure command (M) returns.

Configuring the Operating Mode and Averaging Time

Setting the Operating Mode

The user can select the operating mode of the unit. There parameter that can be either enabled or disabled is background conversions. Background conversion affects the analog output. If background conversion is enabled, the ACCUBAR[®] will continually measure the pressure and update its analog output accordingly. Background conversions add about 7 mA to the quiescent power consumption. With background conversions disabled, the quiescent power consumption of analog units drops to about 1 mA while for digital units it drops to about 0.2 mA. Due to the increased power consumption, the background conversions should not be enabled unless they are needed. If only the analog output is being used and SDI-12 is not being used, then the background conversion must be enabled. If background conversions are disabled then the outputs will only be updated if they are enabled and the ACCUBAR[®] performs a pressure measurement (an M, M1, or M2 command is issued).

If the ACCUBAR[®] is being utilized for both SDI-12 and analog outputs then the user must decide whether they wish the auxiliary output (analog) to match the SDI-12 readings exactly or whether they should be updated independently of SDI-12. To be updated independently means that background conversions must be enabled. To only be updated when SDI-12 readings are performed, the background conversions must be disabled.

The form of the Command is:

aXOMm!	where a is the address character, XOM is the extended command to set the operating mode and <u>m</u> represents the operating mode.
--------	---

The valid values for m are:

- 0 Background operation disabled for analog units. (Low quiescent power consumption for analog units being used as a digital only unit.)
- 16 Continuously update analog output. (Normal operating mode for an analog unit).

Setting the Averaging Time

The ACCUBAR[®] supports user selectable averaging time for SDI-12 readings. The time period in seconds is specified with the aXT+t extended command.

For example, the command

0XT+10!

will set the averaging time to 10 seconds for an ACCUBAR® at address 0.

Note: The averaging time is not the same as the time till completion of a reading. When the ACCUBAR® is awakened by the SDI-12 data recorder and a measurement is requested, the ACCUBAR® calibrates its internal A/D converter before taking the reading. This removes any drift from the analog readings before the pressure measurement is started.

The ACCUBAR® software supports two speed regions. If the requested time is less than 1 second then the unit enters a higher speed mode. In the high accuracy mode ($t > 1$) there is approximately a 3 second overhead involved in the initial calibration before the ACCUBAR® starts the pressure measurement averaging. With the high speed mode the overhead drops to 0.4 seconds.

Note: It is recommended that a measurement be manually initiated (an M, M1, or M2 command) after issuing the XT command to insure that the new coefficients are flushed through the measurement system. This is particularly true with units operating in the background measurement mode. Depending on when the XT command is issued with respect to the background measurement, there is the possibility that the first reading after issuing the XT command will be incorrect.

Resetting the unit to Factory Default Configuration

The ACCUBAR® supports a reset to factory default command. The reset to factory defaults command provides a means to reset most user configurable parameters in a unit back to the factory defaults. If the previous history of a unit is not known, it is recommended that this command be issued before configuring the unit to ensure a known starting configuration.

aXFD!	where a is the address character, XFD is the extended command to reset the unit to the factory default configuration. Note: The address is not changed.
-------	---

Note: It is recommended that the unit be powered down and back up after issuing this command.

A reset to factory defaults sets:

- XUP: Pressure Units to mB (hPa)
- XUT: Temperature Units to Degrees C
- XT: Averaging to one sample in slow mode
- XE: Offset to 0 (may have been previously set by the XS command)
- XOM: To factory default (dependent upon model).
- XOP: To automatically start making readings when an RS-232 connection is made.
- XAR: Resets analog output range 0V = 600 mB, 5 V = 1100 mB
- XUU: Resets user scale factor to 1 and offset to 0

Items not reset:

- Address
- Metrology lab calibration coefficients
- Resolution of pressure data returned as had been set by the XUP command.

5. Command Reference

This chapter documents the commands supported by the ACCUBAR. The commands are listed in alphabetical order within a section.

Accubar Basic SDI-12 Commands

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
	Acknowledge active	<u>a!</u>	<u>a</u>
?	Request Address	<u>?!</u> New in version 1.2 of SDI-12 spec. Also see X? command.	<u>a</u> indicating that the current address is <u>a</u> . Note: ACCUBAR® should be the only sensor on the SDI-12 bus when this command is given, otherwise there will be a communications collision when all units respond.
Ab	Set SDI-12 address (Version 1.9 and higher)	<u>aAb!</u> b new SDI-12 address Example: 5A9! (set address 5 to address 9, the address was previously set to 5)	<u>b</u> indicating that the new address is b. Note: if the DIP switches are set to a non-zero address then upon power-up the address will be the dip-switch address.
C	Request Default Concurrent Pressure Measurement (Version 2.0 and higher)	<u>aC!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready, 02 is the number of values that can be collected <u>axu</u> where x is the signed pressure value and u is the signed indicator of the units. The units are set by the XUP command.
C1	Request Concurrent Pressure Measurement in mB (factory calibrated value) (Version 2.0 and higher)	<u>aC1!</u> <u>aD0!</u>	<u>attt01</u> ttt is the time in seconds until the measurement is ready, 01 is the number of values that can be collected. <u>ap</u> where p is the signed pressure value in mB

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
C2	Request Concurrent Temperature Measurement (Version 2.0 and higher)	<u>aC2!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready and 02 is the number of values that can be collected <u>atu</u> where t is the temperature and u is the units 0=Celsius and 1=Fahrenheit. Use the XUT command to set the units.
C3	Request User Scale, User Offset, and Field Calibration Offset (Version 2.0 and higher)	<u>aC3!</u> <u>aD0!</u>	<u>a00003</u> 000 is the time in seconds until the measurement is ready and 03 is the number of values that can be collected <u>asoc</u> where, s is the user scale and o is the user offset (mB), and c is the field calibration offset (mB).
C4	Request Standards lab Calibration Scale and Offset (Version 2.0 and higher)	<u>aC4!</u> <u>aD0!</u>	<u>a00002</u> 000 is the time in seconds until the measurement is ready and 02 is the number of values that can be collected <u>aso</u> where, s is the scale calibration and o is the offset calibration(mB).

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
C6	Request Concurrent Temperature and Pressure Measurement (Version 2.0 and higher)	<u>aC6!</u> <u>aD0!</u>	<u>attt04</u> ttt is the time in seconds until the measurement is ready and 04 is the number of values that can be collected <u>atupv</u> where t is the temperature, u is the temperature units, p is the pressure, and v is the pressure units. Use the XUT command to set the temperature units and the XUP command to set the pressure units.
C7	Request Concurrent factory calibration Pressure and Temperature Measurement (Version 2.0 and higher)	<u>aC7!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready and 02 is the number of values that can be collected <u>apt</u> where p is the pressure in mB and t is the temperature in degrees Celsius.
CC	Request Default Concurrent Pressure Measurement with CRC-16 (Version 2.0 and higher)	<u>aCC!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready, 2 is the number of values that can be collected <u>axuC</u> where x is the signed pressure value, u is the signed indicator of the units, and C is the 3 character CRC. The units are set by the XUP command.
CC1	Request Concurrent Pressure Measurement in mB with CRC-16 (Version 2.0 and higher)	<u>aCC1!</u> <u>aD0!</u>	<u>attt01</u> ttt is the time in seconds until the measurement is ready, 1 is the number of values that can be collected. <u>apC</u> where p is the signed pressure value in mB and C is the 3 character CRC
CC2	Request Concurrent Temperature Measurement with CRC-16 (Version 2.0 and higher)	<u>aCC2!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>atuC</u> where t is the temperature, u is the units 0=Celsius and 1=Fahrenheit, and C is the 3 character CRC. Use the XUT command to set the units.

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
CC3	Request User Scale, User Offset, and Field Calibration Offset with CRC-16 (Version 2.0 and higher)	<u>aCC3!</u> <u>aD0!</u>	<u>a00003</u> 000 is the time in seconds until the measurement is ready and 3 is the number of values that can be collected <u>asocC</u> where, s is the user scale and o is the user offset (mB), c is the field calibration offset in the current pressure units, and C is the 3 character CRC.
CC4	Request Standards lab Calibration Scale and Offset with CRC-16 (Version 2.0 and higher)	<u>aCC4!</u> <u>aD0!</u>	<u>a00002</u> 000 is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>asoC</u> where, s is the scale calibration, o is the offset calibration(mB), and C is the CRC.
CC6	Request Concurrent Temperature and Pressure Measurement with CRC-16 (Version 2.0 and higher)	<u>aCC6!</u> <u>aD0!</u>	<u>attt04</u> ttt is the time in seconds until the measurement is ready and 04 is the number of values that can be collected <u>atupvC</u> where t is the temperature, u is the temperature units, p is the pressure, v is the pressure units, and C is the CRC. Use the XUT command to set the temperature units and the XUP command to set the pressure units.
CC7	Request Concurrent factory calibration Pressure and Temperature Measurement with CRC-16 (Version 2.0 and higher)	<u>aCC7!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready and 02 is the number of values that can be collected <u>aptC</u> where p is the pressure in mB, t is the temperature in degrees Celsius, and C is the CRC.

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
M1	Request Pressure Measurement in mB (factory calibrated value)	<u>aM1!</u> <u>aD0!</u>	<u>attt1</u> ttt is the time in seconds until the measurement is ready, 1 is the number of values that can be collected. <u>a</u> service request <u>ap</u> where p is the signed pressure value in mB
M2	Request Temperature Measurement	<u>aM2!</u> <u>aD0!</u>	<u>attt2</u> ttt is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>a</u> service request <u>atu</u> where t is the temperature and u is the units 0=Celsius and 1=Fahrenheit. Use the XUT command to set the units.
M3	Request User Scale, User Offset, and Field Calibration Offset	<u>aM3!</u> <u>aD0!</u>	<u>a0003</u> 000 is the time in seconds until the measurement is ready and 3 is the number of values that can be collected <u>asoc</u> where, s is the user scale and o is the user offset, and c is the field calibration offset. The field calibration is returned in the current units.
M4	Request Standards lab Calibration Scale and Offset	<u>aM4!</u> <u>aD0!</u>	<u>a0002</u> 000 is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>aso</u> where, s is the scale calibration and o is the offset calibration(mB).

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
M6	Request Temperature and Pressure Measurement (Version 2.0 and higher)	<u>aM6!</u> <u>aD0!</u>	<u>attt4</u> ttt is the time in seconds until the measurement is ready and 4 is the number of values that can be collected <u>a</u> service request <u>atupv</u> where t is the temperature, u is the temperature units, p is the pressure, and v is the pressure units. Use the XUT command to set the temperature units and the XUP command to set the pressure units.
M7	Request factory calibration Pressure and Temperature Measurement (Version 2.0 and higher)	<u>aM7!</u> <u>aD0!</u>	<u>attt2</u> ttt is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>a</u> service request <u>apt</u> where p is the pressure in mB and t is the temperature in degrees Celsius.
MC	Request Default Pressure Measurement with CRC-16 (Version 2.0 and higher)	<u>aMC!</u> <u>aD0!</u>	<u>attt2</u> ttt is the time in seconds until the measurement is ready, 2 is the number of values that can be collected <u>a</u> service request <u>axuC</u> where x is the signed pressure value, u is the signed indicator of the units, and C is the 3 character CRC. The units are set by the XUP command.
MC1	Request Pressure Measurement in mB with CRC-16 (Version 2.0 and higher)	<u>aMC1!</u> <u>aD0!</u>	<u>attt1</u> ttt is the time in seconds until the measurement is ready, 1 is the number of values that can be collected. <u>a</u> service request <u>apC</u> where p is the signed pressure value in mB and C is the 3 character CRC

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
MC2	Request Temperature Measurement with CRC-16 (Version 2.0 and higher)	<u>aMC2!</u> <u>aD0!</u>	<u>attt2</u> ttt is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>a</u> service request <u>atuC</u> where t is the temperature, u is the units 0=Celsius and 1=Fahrenheit, and C is the 3 character CRC. Use the XUT command to set the units.
MC3	Request User Scale, User Offset, and Field Calibration Offset with CRC-16 (Version 2.0 and higher)	<u>aMC3!</u> <u>aD0!</u>	<u>a0003</u> 000 is the time in seconds until the measurement is ready and 3 is the number of values that can be collected <u>asocC</u> where, s is the user scale and o is the user offset (mB), c is the field calibration offset (current pressure units), and C is the 3 character CRC.
MC4	Request Standards lab Calibration Scale and Offset with CRC-16 (Version 2.0 and higher)	<u>aMC4!</u> <u>aD0!</u>	<u>a0002</u> 000 is the time in seconds until the measurement is ready and 2 is the number of values that can be collected <u>asoC</u> where, s is the scale calibration, o is the offset calibration (mB), and C is the 3 character CRC.

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
MC6	Request Temperature and Pressure Measurement with CRC-16 (Version 2.0 and higher)	<u>aMC6!</u> <u>aD0!</u>	<u>attt04</u> ttt is the time in seconds until the measurement is ready and 04 is the number of values that can be collected <u>a</u> service request <u>atupvC</u> where t is the temperature, u is the temperature units, p is the pressure, v is the pressure units, and C is the 3 character CRC. Use the XUT command to set the temperature units and the XUP command to set the pressure units.
MC7	Request factory calibration Pressure and Temperature Measurement with CRC-16 (Version 2.0 and higher)	<u>aMC7!</u> <u>aD0!</u>	<u>attt02</u> ttt is the time in seconds until the measurement is ready and 02 is the number of values that can be collected <u>a</u> service request <u>aptC</u> where p is the pressure in mB, t is the temperature in degrees Celsius, and C is 3 character CRC.
R0 R1 . . . R9	Request Continuous Measurement Readings	<u>aR0!</u> <u>aR1!</u> . . . <u>aR9!</u>	<u>a</u> Unit only returns its address because it does not support continuous measurements.
V	Initiate Verify sequence	<u>aV!</u> <u>aD0!</u>	<u>attt5</u> indicating that the command will be complete in ttt seconds and 5 values can be collected. <u>a</u> service request <u>arespu</u> where r is the ROM checksum, e is the EEROM checksum, s is the number of resets since power up, p is the number of power ups, and u is the number of unexpected interrupts.

Accubar Extended Commands

	Command Description	Command Syntax (command underlined)	Sensor response (underlined) "a" represents the single-character address
X?	Request unknown address	<u>*X?!</u> This command causes any Sutron ACCUBAR [®] to identify itself. If you have more than one ACCUBAR [®] connected, the result may be garbled. There is no guarantee that non-ACCUBAR [®] devices will respond to this command.	<u>a</u> Accubar's address.
XAD	Set SDI-12 address (Sutron extended version) see A command for SDI-12 standard version.	<u>aXADnAn!</u> n new SDI-12 address, repeated twice Example: 5XAD9A9! (set address 5 to address 9, the address was previously set to 5)	<u>a0011</u> no response if addresses do not match Note: if the DIP switches are set to a non-zero address then upon power-up the address will be the dip-switch address. Note: a D0 command issued to the new address after the XAD command will return the new address.
XE	Set Elevation offset	<u>aXExu!</u> where x is the pressure offset u indicates the units of the offset, 0=mB (hPa), 1="Hg, 2=kPa, 3=mmHg, 4=Atm, 5=psia, or 9=user units. Example: 0XE+20.05+0 (set elevation offset to +20.05 mB) Note Version 2.0 and later: Offset can be queried by issuing aXE! Followed by a aD0!	<u>a0011</u> indicating that the command will take 1 second and 1 value can be collected. <u>a</u> service request Note: a D0 command issued after the XE command will return the offset in units of mB (hPa) for software versions before 2.0. Version 2.0 and later return the offset in the current units of pressure.
XFD	Reset to Factory defaults	<u>aXFD!</u> This command resets most user configurable configuration items back to the factory defaults. It does not reset the address nor does it affect metrology lab calibrations. Note: It is recommended that the unit be powered down and back up after use of this command.	<u>a0101</u> indicating that the command will take 10 seconds and 1 value can be collected. <u>a</u> service request Note: a D0 command issued after the XFD command will return the operating mode

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
XOP	Set Operating Parameters (Version 2.1 and higher)	<u>aXOPp!</u> where p is the desired operating parameter to be set. values for p 0 Factory default condition which starts reporting pressure readings when an RS-232 connection is made. 1 Disable automatic reading mode for RS-232 All input values are standard SDI-12 values with polarity sign	<u>attt1</u> where ttt indicates the command will be complete in ttt seconds and 1 indicates one value can be collected. Note: a D0 command issued after the XOP will return the current operating parameters.
XS	Self-Cal the Elevation Offset	<u>aXSdu!</u> where d is the desired reading for the sensor and in the units indicated by u. The ACCUBAR® will make repeated measurements and adjust the elevation offset to insure the reading matches the value entered. Example: 0XS+1007.9+0 (sensor is at 1007.9 mB, adjust offset to insure this reading)	<u>attt1</u> where ttt indicates the command will be complete in ttt seconds and 1 indicates one value can be collected. Note: a D0 command issued after XS is complete will display the new offset in units of mB for software versions prior to 2.0. Version 2.0 and later return the offset in the current units of pressure. The offset can also be displayed using the M3 command.
XT	Set Averaging Time (Version 1.5 and higher)	<u>aXT+t!</u> t = averaging time in seconds (0 to 240 seconds) Example: 0XT+10! (sets the averaging time to 10 seconds)	<u>a0011</u> indicating the command will be complete in 1 second and 1 value can be collected Note: a D0 command issued after the XT will return the number of samples to be averaged during the selected time.

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
XUP	Set pressure units (Version 1.5 and higher for setting number of decimal places)	<u>aXUP+n+d!</u> n = 0 mB (hPa) n = 1 "Hg n = 2 kPa n = 3 mmHg n = 4 Atm n = 5 psia n = 9 user units d = number of places right of the decimal (optional parameter) Example: 0XUP+9+2! Select user units with 2 right digits-- (make sure you use XUU command to set the scale and offset for the desired user units)	<u>a0012</u> indicating the command will be complete in 1 second and 2 values can be collected Note: a D0 command issued after the XUP will return the value of the units that are selected and the number of digits right of the decimal point. Note Version 2.0 and higher: Current settings can be queried by issuing the aXUP! Command followed by the aD0! Command.
XUT	Set temperature units	<u>aXUTn!</u> n = 0 for Celsius, n = 1 for Fahrenheit Example: 0XUT1! (set temperature units to F) Note Version 2.0 and higher: Current settings can be queried by issuing the aXUT! Command followed by the aD0! Command.	<u>a0011</u> indicating the command will take 1 second to complete and 1 value can be collected. Note: a D0 command issued after the XUT will return the value of the units that are selected.
XUU	Set User Units	<u>aXUUso!</u> where s is the pressure scale factor and o is the offset, User output = (mB)*scale + offset Example: 0XUU+27.63+0 (27.63 user units per mB) Note Version 2.0 and higher: Current settings can be queried by issuing the aXUU! Command followed by the aD0! Command.	<u>a0012</u> Note: a D0 command issued after XUU will return the scale and offset. Note: a scale of 0 is invalid. Note: Be sure that the units of pressure (XUP) are set to user units (9).

Additional commands for Analog output units (-2)

	Command Description	Command Syntax (command underlined)	ACCUBAR® response (underlined) "a" represents the single-character address
XAR	Set Analog Output range	<p><u>aXARzf!</u> where z is the pressure in mB or hPa to be represented by 0.000 VDC</p> <p>f is pressure in mB or hPa to be represented by 5.000 VDC</p> <p>All input values are standard SDI-12 values with polarity sign.</p>	<p><u>a0012</u> indicating the command will be complete in one (1) second and that two (2) values can be collected.</p> <p>NOTE: A D0 command issued after the XAR will return two (2) values representing the pressure range that the user has selected.</p> <p>Note Version 2.0 and higher: Current settings can be queried by issuing the aXAR! Command followed by the aD0! Command.</p>
XAO	Set Analog Output to a fixed voltage	<p><u>aXAOv!</u> where v is the required output in VDC</p> <p>All input values are standard SDI-12 values with polarity sign</p>	<p><u>a0011</u> indicating that the command will take one (1) second to complete and that one (1) value can be collected</p> <p>NOTE: A D0 command issued after the XAO command will return the D/A value corresponding to the requested voltage.</p> <p>The unit's output will not act as a pressure sensor again until this same command is given with a negative voltage request.</p>
XOM	Set operating mode	<p><u>aXOMm!</u> where m is the desired operating mode. values for m</p> <p>0 Background operation disabled. (Low quiescent power consumption for analog units being used as a digital only unit.)</p> <p>16 Continuously update analog output.</p> <p>All input values are standard SDI-12 values with polarity sign</p>	<p><u>attt1</u> Indicating that the command will take ttt seconds to complete and that one (1) value can be collected</p> <p>NOTE: A D0 command issued after the XOM command will return the set operating mode.</p> <p>Note Version 2.0 and higher: Current settings can be queried by issuing the aXOM! Command followed by the aD0! Command.</p>

6. Installation

The ACCUBAR[®] will return accurate and reliable pressure data in any mounting position. We recommend, however, mounting the sensor with the connector and cable gland pointing downward. This will prevent any moisture from following the cable or tubing down to the ACCUBAR[®] sensor.

The ACCUBAR[®] mounts to a panel or surface through two holes that are accessible under the sensor cover. The through-holes accommodate #8, #6 or M4 hardware.

The ACCUBAR[®] barometric pressure fitting is a hose barb for a 3/16" ID tubing.

The terminal block accommodates wire sizes from 28 AWG to 16 AWG or up to 1 mm². The recommended length of bare wire is 0.22" or 5.5 mm.

7. Calibration

The Accubar under goes a rigorous screening and testing at the factory before it is shipped to ensure that it meets the accuracy specifications over temperature and that it is stable both in zero and span and will continue to be accurate over time. The drift of the ACCUBAR[®] in the field is typically less than 0.05 mB per six months. This is a small fraction of the stated accuracy of the Accubar. The stated accuracy of the ACCUBAR[®] is 0.5 mB, although typically it is much better. Even though it would typically take over 5 years for the ACCUBAR[®] to drift as much as 0.5 mB, it is recommended that the Accubar, like all precision measurement instruments, be placed on a periodic calibration schedule.

Factory Calibration

The initial factory calibration typically includes over 600 different pressure temperature points that cover the complete temperature range from -40 to +60 degrees C and cover the complete pressure range from 600 to 1100 mB. This ensures that the ACCUBAR[®] meets the specifications over the complete pressure and temperature range. A calibration verification encompasses nearly 300 points over the complete temperature and pressure range. An Accubar can be sent back to the factory for a complete calibration over temperature. The Sutron Part number for this calibration service is: 8700-0005

Metrology Lab Calibration

The ACCUBAR[®] does have the provision for a calibration to be performed by a Metrology Lab. The calibration coefficients that can be entered by a metrology lab are a scale and an offset parameter. There is not a provision for any temperature dependent parameters. Most metrology labs would not have the capabilities to provide a calibration over temperature and pressure. To accurately calibrate an ACCUBAR[®] requires a reference accuracy on the order of 0.1 mB.

To collect data for calibration of the Accubar, the M1 command should be utilized. This will ensure that field offset or old calibration coefficients do not affect the accuracy of the data collected. The command that is utilized to enter the Metrology Lab Coefficients is:

aXCosc!	where a is the address character, XC is the extended command to set the calibration coefficients, o is the offset in mB, s is the scale factor, and c is the checksum.
---------	--

The Checksum is the 8 bit sum of the 7 bit ASCII characters (parity is striped) from and including the address character through the last character of the scale factor. It does not include the checksum string nor its delimiting polarity sign. The checksum is transmitted as an ASCII string. That means that if the 8-bit sum is 236 then the value of c is +236. The command to set the offset of the unit at address 0 to 0.0000 and the scale factor to 1.0000 would be:

0XC+0+1+130!

The calibration coefficients affect the output of the M command, the RS-232 output, the analog output, and the quadrature output. This command does not affect the output of the M1 command. The data output by the M command is computed from the following equation:

Pressure = units offset + units scale * (field offset + calibration scale *(press. in mB - calibration offset))

where:

- press. in mB is the factory calibration pressure as returned by the M1 command.
- calibration offset is entered by the XC command
- calibration scale is entered by the XC command
- field offset is entered by the XE or XS commands
- units scale and units offset are set by the combination of the XUP and XUW commands.

Note: Calibration scale and calibration offset can be determined via the M4 command.

Note: The current value of field offset, user units offset, and user units scale can be determined via the M3 command.

8. Troubleshooting and Maintenance

Troubleshooting

The following checklist will help in troubleshooting problems:

Problem	Possible Cause
No data	Faulty wiring -- check all wiring and terminations
	No power -- check fuse in the data recorder and power at sensor. There is no fuse in the sensor itself.
	Wrong address requested -- make sure the data recorder is set up to request data at the proper address
	Wrong address set in sensor -- use the identify command to make sure the sensor is responding to the proper address, if not double check internal address dip switches since on power-up they override any address set by the software.
	Command or address is wrong case -- all ACCUBAR [®] commands are capital letters, make sure address is proper case and commands are upper case.
	With RS-232, make sure that Transmit and Receive Data are not reversed.
Garbled data	Multiple sensors set to the same address -- check address settings of all SDI sensors. Remove all other sensors from the recorder and add them one at a time. Communication is defined to be 1200, E, 7, 1.
	Command issued to a wild card address (* or ?). Remove all other sensors from the recorder and try again.
Erroneous data	Wrong units selected -- use the M command and look at the units field. Verify that the desired units are selected.
	Erroneous offset entered -- display the elevation offset using the M3 command and verify it. Re-calibrate the offset.
	Erroneous user scale and offset entered -- display the user scale and offset using the M3 command and verify.

CAUTION: Do not remove the microprocessor from the ACCUBAR[®] for any reason. If there is a problem with the processor, please notify Sutron Customer Service at (703) 406-2800. Only factory-trained personnel with specialized tools can remove the microprocessor without damaging the unit and the processor.

Also note that each microprocessor has been characterized for the specific unit in which it is placed; THEY ARE NOT INTERCHANGEABLE.

Additional Troubleshooting commands

Measure Break detect time

The SDI-12 specification requires that all sensors ignore breaks less than 6.5mS and states that they must detect breaks that are at least 12mS in length. There is an RS-232 command for the unit to measure its break detect time. The unit should be completely disconnected from the SDI-12 bus and the command issued via the RS-232 interface. Note: The unit will ignore this command if issued via SDI-12.

aXB!	where a is the address character, XB is the extended command to measure the break detect time. Returns: adr where d is the break detect time and r is the break reset time
------	---

The break detect time should be between 6.5 and 8.5 milliseconds and the break reset time should be less than 1 millisecond.

Test Analog output

aXAT+v+n!	where a is the address character, XAT is the extended command to test the analog output, v is the maximum value to output, and n is the number of times to repeat the cycle.
-----------	--

It ramps the analog output down from the value indicated by v to 0 and then repeats the process n times. The output signal when observed with an oscilloscope will be a saw tooth wave form when the analog output is working properly. The valid range for v is 0 to 4095. The valid range for n is 0 to 255. Note: This command can only be issued over the RS-232 interface. If issued over the SDI-12 interface it will be ignored. Note: A value of 0 for v will produce a zero volt signal while a value of 4095 will produce a saw-tooth waveform that starts slightly above 5 volts and ramps to zero.

Maintenance

Typical maintenance for the sensor consists of checking the wiring to make sure it is not corroded or frayed, checking the tubing to make sure it is intact and leak-free, and checking or setting the elevation offset.

Maintenance should be performed at least every 6 months in order to insure that the sensor meets the accuracy specifications.

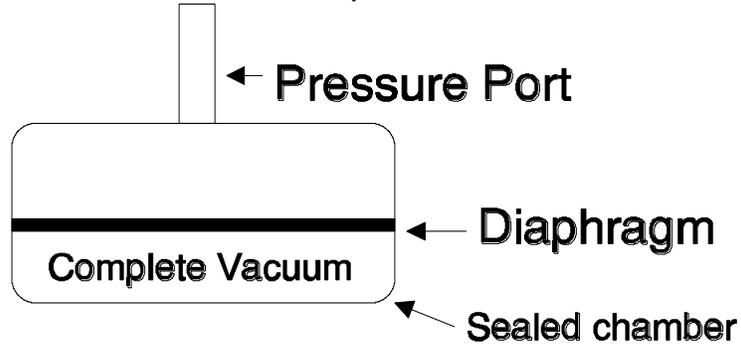
9. Specifications for 5600-0120 Barometric ACCUBAR®

Dimensions	3.14" X 2.95" X 2.24"
Weight	<1 lb.
Range	500 to 1100mB (hPa) 14.8 to 32.5" Hg
Elevation	-2300 to 18,300 feet (-700 to 5600 meters)
Operating Temp Range	-40°C to +60°C
Vibration	0.5g @ 10-50Hz
Accuracy	0.5mB (hPa) over temperature range
Resolution	0.01mB
Averaging Time	0 to 240 seconds (user selectable)
Supply Voltage	+8 to +28VDC (reverse polarity protected)
Power Consumption	
RS-232 (active)	18mA typ.
SDI-12 (active)	7mA typ.
Quiescent (-1)	0.2mA typ.
Quiescent (-2)	0.8mA typ.
Output	
Standard (-1)	RS-232 and SDI-12
Optional (-2)	RS-232, SDI-12, and Analog 0-5 VDC
Data Output	Continuous or on-demand
Default Data Format RS-232	#####.## <CR> <LF>
Communication Rate	1200 baud
Pressure Units Supported	mB,hPa,kPa,"Hg,mm Hg,ATM,psi
Pressure Fitting	Hose barb for 3/16" ID hose
Electrical Connection	Cable gland for 1/4" cable to terminal block for 16-- 28 AWG wire

TYPES OF PRESSURE MEASUREMENTS

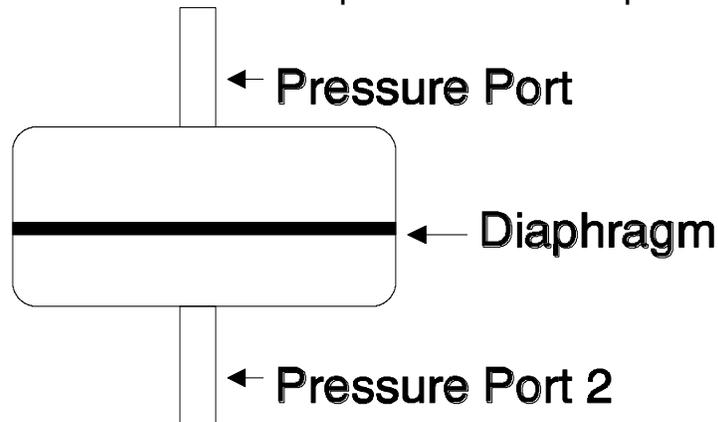
ABSOLUTE (PSIA)

Pressure is measured with respect to an absolute vacuum.



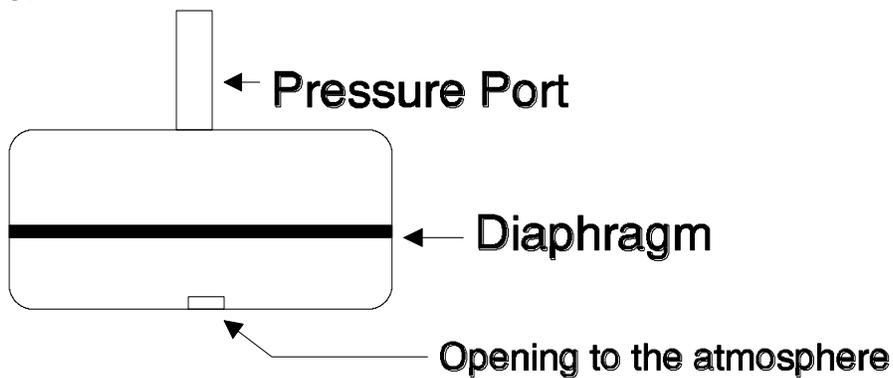
DIFFERENTIAL (PSID)

Pressure is measured with respect to a second pressure port.



GAUGE (PSIG)

Pressure is measured with respect to atmospheric pressure. Same as a differential pressure sensor with the second port open to the atmosphere.



PRESSURE UNITS

BAROMETRIC

PSIA	pounds per square inch absolute (industrial units)
mB	millibars
hPa	hectoPascals (WMO unit of measure)
mmHg	millimeters of mercury at 0 degrees C (scientific units)
"Hg	inches of mercury at 0 degrees C (common US unit)
ATM	Atmospheres
torr	same as millimeters of mercury

PRESSURE EQUIVALENTS						
millibars	hPa	"Hg	PSI	mmHg	ATM	altitude in ft.
1100	1100	32.483	15.954	825.07	1.0856	-2291
1050	1050	31.006	15.229	787.56	1.0363	-989
1013.3	1013.3	29.921	14.696	760.00	1.0000	0
1000	1000	29.530	14.504	750.06	0.9869	364
950	950	28.053	13.779	712.56	0.9376	1773
900	900	26.577	13.053	675.05	0.8882	3243
850	850	25.100	12.328	637.55	0.8389	4781
800	800	23.624	11.603	600.05	0.7895	6394
750	750	22.147	10.878	562.55	0.7402	8091
700	700	20.671	10.153	525.04	0.6908	9882
650	650	19.194	9.427	487.54	0.6415	11780
600	600	17.718	8.702	450.04	0.5922	13800

GAUGE

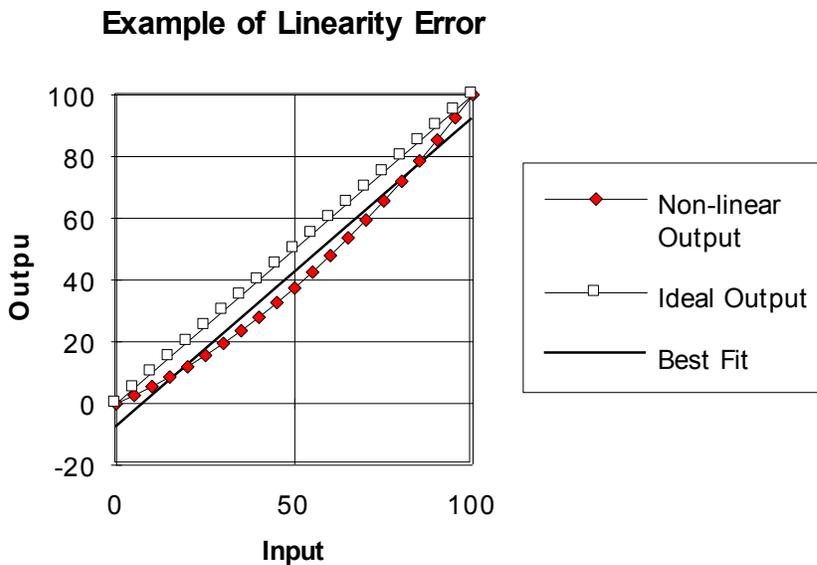
PSIG or PSI	pounds per square inch
feet of water	(USGS conversion factor is 2.3073 * PSI)

PRESSURE EQUIVALENTS		
PSI	feet of Water	kPa
0	0.000	0.000
5	11.537	34.474
10	23.073	68.948
15	34.610	103.421
20	46.146	137.895
22	50.761	151.685
35	80.756	241.317

ERROR DEFINITIONS AND EXAMPLES

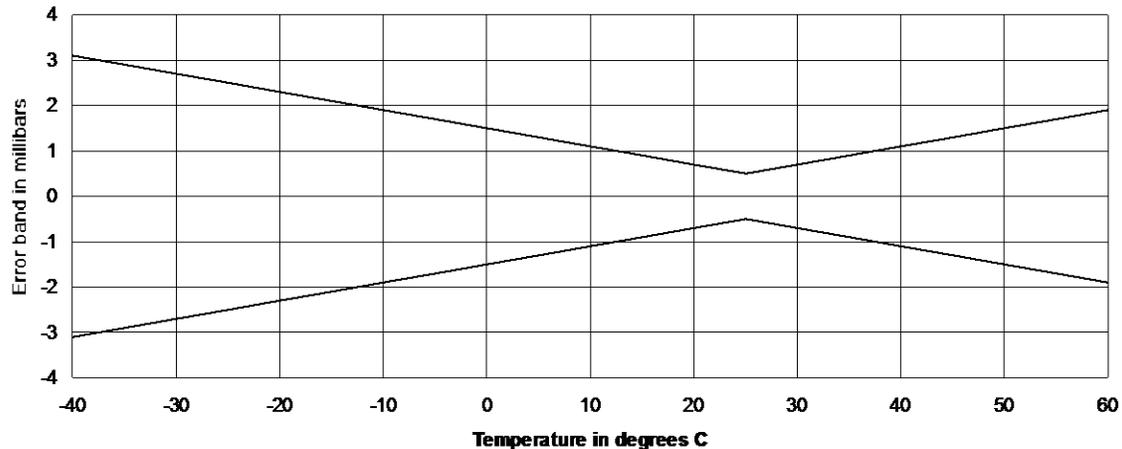
Linearity:

Linearity error is the deviation of the output from a straight line. Many transducers for measuring physical phenomena have outputs which do not vary linearly with the phenomena being measured. Sometimes the deviation from linear is slight and is accepted as part of the error of the device, in other cases manufacturers attempt to "linearize" the output. Usually when this done through an analog means, there will be a residual non-linearity, i.e., the non-linearity is not completely removed. The following non-linearity graph illustrates why a two point calibration (zero and full scale) is many times insufficient and ensures that the maximum error is achieved. A best fit straight line decreases the maximum error by ensuring that the errors fall evenly on both sides.



Temperature coefficient -- This is made up of two components, the temperature coefficient of the offset and the temperature coefficient of the slope. These can be referred to as thermal shifts, temperature dependence, and other names. The offset is sometimes referred to as zero. The slope is sometimes referred to as span, sensitivity, or scale factor. The following graph illustrates why the temperature coefficient is an important specification for remote equipment. In an indoor environment a competitor's barometer is about a 0.5 mB instrument. Over the operating temperature range of Sutron equipment, it degrades to a ± 3 mB instrument.

Example Temperature error of a Competitor's 0.5 mB "Accurate" Barometer



Hysteresis - This is a measure of deviation in the output when passing through an input point from two different directions. If a pressure transducer has zero pressure applied, then 10 PSI, then 22 PSI, then 10 PSI, the difference between the two 10 PSI readings would be a measure of the pressure hysteresis of the transducer. Pressure transducers can also have temperature hysteresis errors. Sometimes hysteresis is lumped in with other non-repeatability errors.

ACCURACY - Accuracy is a measure of how closely the sensor's output matches the "true" value of the parameter being sensed.

PRECISION - Precision is a measure of the repeatability of the sensor. It will most always be better than the accuracy of the sensor.

RESOLUTION - The resolution of a sensor is the smallest change in the input that is reflected in the output. For digital sensors it also refers to the smallest increment of the output. This may be greater than or less than the sensor's resolution with respect to its input. Greater resolution does not imply greater accuracy. Resolution and Accuracy are two independent variables. The advantage of resolution in excess of accuracy is that changes in the input parameter can be detected and tracked.

Appendix B– Sutron Customer Service Policy

CUSTOMER SERVICE POLICY

Dear Customer:

Thank you for making the important decision to purchase Sutron equipment. All Sutron **equipment is manufactured and tested to the highest quality standards as set by Sutron's** Quality Assurance Department. Our Customer Service Representatives have years of experience with equipment, systems, and services. We have electronic technicians with field and applications experience, not limited to technical school training.

Customer Phone Support

Customer Service Representatives routinely handle a wide variety of questions every day. If questions arise, please feel free to contact me or one of the Customer Service Representatives. We are available from 8:00 am to 5:00 pm Monday through Friday and will be happy to take your call.

We can answer most sensor and interface questions on the first call. If we cannot quickly answer a question on an interface, we will work with you until we find a solution.

Sometimes a problem is application related. Although we pride ourselves on handling 95% of application related questions over the phone, we maintain constant contact with our Integrated Systems Division and Engineering Division for additional assistance.

Training

Training is an important part of the Sutron Customer Service philosophy. Without the proper training, you cannot take advantage of the benefits and advantages that Sutron equipment provides. We often supply on-site introductory training at your facility. We also hold a 3 day training seminar 4 times each year at our Sutron headquarters in Sterling Va. Contact me or your Sutron Regional Sales Manager for details.

On-Site Visits

Of course not all problems can be fixed over the phone. Sometimes a customer needs an on-site technician to identify site related problems or troubleshoot a network. Sutron can provide these services at a reasonable cost. Call for details. If you would like to learn more about Sutron products email sales@sutron.com

Thanks again for your order,

Paul Delisi
Customer Service Manager
Sutron Corporation
pdelisi@sutron.com

Appendix C– Commercial Warranty

SUTRON MANUFACTURED EQUIPMENT

THE SUTRON CORPORATION WARRANTS that the equipment manufactured by its manufacturing division shall conform to applicable specifications and shall remain free from defects in workmanship and material for a period ending two years from the date of shipment from Sutron's plant.

Sutron's obligation under this Warranty shall be limited to repair at the factory (22400 Davis Drive, Sterling, VA 20164), or at its option, replacement of defective product. In no event shall Sutron be responsible for incidental or consequential damages, whether or not foreseeable or whether or not Sutron has knowledge of the possibility of such damages. This warranty shall not apply to products that have been damaged through negligence, accident, misuse, or acts of nature such as floods, fires, earthquakes, lightning strikes, etc.

Sutron's liability, whether in contract or in tort, arising out of warranties or representations, instructions or defects from any cause, shall be limited exclusively to repair or replacement parts under the aforesaid conditions.

Sutron requires the return of the defective electronic products or parts to the factory to establish claim under this warranty. The customer shall prepay transportation charges to the factory. Sutron shall pay transportation for the return of the repaired equipment to the customer when the validity of the damage claim has been established.

Otherwise, Sutron will prepay shipment and bill the customer. All shipments shall be accomplished by best-way surface freight. Sutron shall in no event assume any responsibility for repairs or alterations made other than by Sutron. Any products repaired or replaced under this warranty will be warranted for the balance of the warranty period or for a period of 90 days from the repair shipment date, whichever is greater. Products repaired at cost will be warranted for 90 days from the date of shipment.

NON-SUTRON MANUFACTURED EQUIPMENT

The above Warranty applies only to products manufactured by Sutron. Equipment provided, but not manufactured by Sutron, is warranted and will be repaired to the extent of and according to the current terms and conditions of the respective equipment manufacturers.

REPAIR AND RETURN POLICY

Sutron maintains a repair department at the factory, 22400 Davis Drive, Sterling, VA 20164. Turn around time normally ranges from 10-30 days after Sutron receives equipment for repair. **Call Customer Service at (703) 406-2800 for a Return Material Authorization (RMA) number.** Return the defective equipment to the factory, transportation charges paid.

EXTENDED WARRANTY AND ON-SITE MAINTENANCE

Extended warranty and on-site maintenance contracts are available. Price quotations may be obtained from Sutron customer service representatives.